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B_1 -EPG representations using block-cutpoint trees

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Abstract. In this paper, we are interested in the edge intersection graphs of paths of a grid where each path has at most one bend, called B_1 -EPG graphs and first introduced by Golumbic et al (2009). We also consider a proper subclass of B_1 -EPG, the \lfloor -EPG graphs, which allows paths only in " \lfloor " shape. We show that two superclasses of trees are B_1 -EPG (one of them being the cactus graphs). On the other hand, we show that the block graphs are \lfloor -EPG and provide a linear time algorithm to produce \lfloor -EPG representations of generalization of trees. These proofs employed a new technique from previous results in the area based on block-cutpoint trees of the respective graphs.

Keywords. Edge intersection graph, Block-cutpoint trees, Block graphs, Cactus graphs.

1 Introduction

Let \mathcal{P} be a family of nontrivial paths on a rectangular grid \mathcal{G} . We define the *edge intersection* graph EPG(\mathcal{P}) of \mathcal{P} as the graph whose vertex set is \mathcal{P} and such that (P, Q) is an edge of EPG(\mathcal{P}) if and only if paths P and Q share at least one grid edge of \mathcal{G} . A graph G is called an *edge intersection graph of paths on a grid (EPG)* if $G = EPG(\mathcal{P})$ for some family of paths \mathcal{P} on a grid \mathcal{G} , and \mathcal{P} is an *EPG representation* of G. EPG graphs were first introduced by Golumbic et al in [6] motivated from circuit layout problems [4]. Figure 1 illustrates the EPG-graph corresponding to the family of paths presented in the figure.

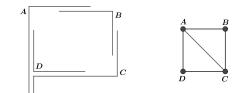


Figure 1: A B₂-EPG representation \mathcal{P} and its corresponding EPG graph EPG(\mathcal{P}).

A turn of a path at a grid point is called a *bend* and the grid point in which a bend occurs is called a *bend point*. An EPG representation is a B_k -EPG representation if each path has at most k

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bends. A graph that has a B_k -EPG representation is called B_k -EPG. Therefore, the graph defined in Figure 1 is B_2 -EPG, as the representation shows. However, it is possible to show that there is a B_1 -EPG representation of G and, thus, G is also B_1 -EPG. The time complexity of recognizing B_k -EPG is polynomial for k = 0 [6], and NP-hard for k = 1 [8] and k = 2 [10], whereas is unknown for other values of k.

A block B of a graph G is a maximal biconnected subgraph of G. A vertex v of a connected graph G is a cut vertex if G - v is disconnected. For a graph G, we define its block-cutpoint tree [7] (BC-tree) T as follows. There is a vertex in T corresponding each block of G, called a block vertex, and a vertex for each cut vertex of G, called as such in T. A cut vertex c forms an edge with a block vertex b if the block corresponding to b contains c in G. The only existing vertices and edges of T are those previously described. Figure 2 depicts a graph and its respective BC-tree.

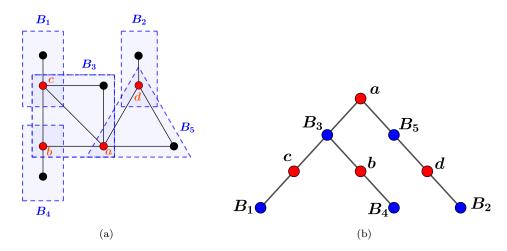


Figure 2: A graph and its respective BC-tree. The cut vertices are marked in red.

A universal vertex is a vertex of G that is adjacent to all other vertices of G. For $X \subseteq V(G)$, we denote by G[X] the subgraph induced by X. A cycle with k vertices is denoted by C_k .

In B₁-EPG representations, each path has one of the following shapes: $_, \ulcorner, \lrcorner, \urcorner$, besides horizontal or vertical segments. One may consider more restrictive subclasses of B₁-EPG by limiting the type of bends allowed in the representation. This arises the definition of "x"-EPG graphs, where "x" stands for a sequence of path shapes allowed in the class. For example, the $_\urcorner$ -EPG graphs are those in which only the " $_$ " or the " \urcorner " shapes are allowed. Although that might imply the study of 2⁴ different subclasses, corresponding to all subsets of { $_, \ulcorner, \lrcorner, \urcorner$ }, only the $_$ -EPG, $__$ -EPG and $__$ [¬]-EPG may be considered, since all others do not define distinct subclasses (their representations are isomorphic to these four up to 90 degree rotations and reflections).

2 A B_1 -EPG representation of a superclass of trees

In this section, we describe a B_1 -EPG representation of a superclass of trees, inspired on the representation of trees described in [6]. The novelty of the following results are the usage of BC-trees to obtain EPG representations.

Theorem 1. Let G be a graph such that every block of G is B_1 -EPG and every cut vertex v of G is a universal vertex in the blocks of G in which v is contained. Then, G is B_1 -EPG.

Proof. The result is trivial if G does not have cut vertices, since G consists of a single block. Therefore, we assume from now on that there is a cut vertex in G. The theorem is proved by induction. Actually, we prove a stronger claim, stated as follows: given any graph G satisfying the theorem conditions and a BC-tree T of G rooted at some cut vertex r, there exists a B₁-EPG representation $\mathcal{R} = \{P_v \mid v \in V(G)\}$ of G in which:

- (i) P_r is a vertical path with no bends in \mathcal{R} ;
- (ii) all paths but P_r are constrained within the horizontal portion of the grid defined by P_r and at the right of it.

Let B_1, B_2, \ldots, B_t be the block vertices which are children of r and let $T_{i1}, T_{i2}, \ldots, T_{ij_i}$ be the subtrees rooted at B_i , for all $1 \leq i \leq t$ (see Figure 3). The leaves of T are the blocks of Ghaving exactly one cut vertex. From T, build the representation \mathcal{R} of G as follows. First, build an

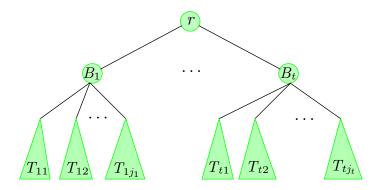


Figure 3: The rooted BC-tree T of a graph.

arbitrary vertical path P_r in the grid \mathcal{G} , corresponding the root r. Next, divide the vertical portion of \mathcal{G} defined by P_r and at the right of it into t vertical subgrids, $\mathcal{G}_1, \mathcal{G}_2, \ldots, \mathcal{G}_t$, with a row space between them such that the *i*-th subgrid will contain the paths corresponding to the cut vertices that are descendants of B_i in T. So, each subgrid \mathcal{G}_i is constructed as follows. We first represent the children of B_i as disjoint τ -shaped paths, all sharing the same grid column in which P_r lies, since by the hypothesis, the children of B_i are all adjacent to r. Now, for each B_i , we build the following paths:

- those corresponding to vertices of B_i that are not cut vertices of G (as those vertices in black in Figure 2(a)); let us call the set of such vertices as B'_i ;
- those belonging to the induced subgraphs of G corresponding to the BC-trees $T_{i1}, T_{i2}, \ldots, T_{ij}$.

These paths will be placed on the marked regions of G_i of Figure 4. So, it remains to define how the paths belonging to the regions B'_i and T_{ij} will be build, for all $1 \le j \le j_i$.

So, by the claim hypothesis, r is universal to B_i and B_i is a B₁-EPG graph. Therefore, let \mathcal{R}' be a B₁-EPG representation of B_i . Without loss of generality, considering the operation of rotating the representation, let P'_r be an $_$ -path corresponding r in \mathcal{R}' and let p be its bend point. Since r is universal to B_i , all other paths must share a grid edge with P'_r . Transform \mathcal{R}' in the following way:

- For all P'_z , a path of \mathcal{R}' that intersects all other paths of \mathcal{R}' and is not coincident to P'_r , modify P'_z by making it coincident to P'_r .

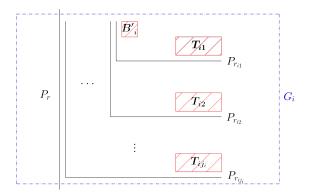


Figure 4: A subgrid G_i .

- For all P'_z , a path of \mathcal{R}' which contains p and the grid point immediately below of p, modify P'_z by removing the part of the path that goes from p downwards (that is, making p an endpoint of P'_z). Such a modification does not change the intersections of P'_z . Clearly, by construction, it does not increase the intersections. To see that it does not decrease as well, note that if P'_z lost an edge intersection to some path P'_w , it is because P'_w would intersect P'_z only in the "leg" that was removed, which would imply that P'_w does not intersect P'_r , an absurd.
- For all P'_z , a path of \mathcal{R}' which contains p and the grid point immediately at the left of p, modify P'_z in an analogous way, removing the part of the paths that are to the left of p.

Finally, \mathcal{R}' can be transformed such that all universal vertices become vertical paths, by "unbending" them at the grid point p (see Figure 5).

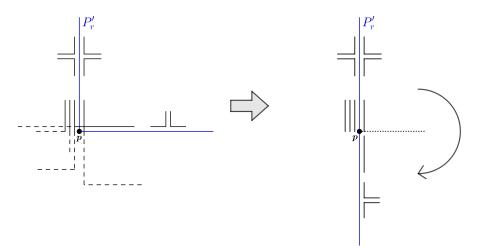


Figure 5: Transformations of P'_z .

For the T_{ij} portion of the representation, let r_{ij} be the root of T_{ij} . Applying induction hypothesis, we obtain B₁-EPG representations of each subtree that have vertical paths representing each root and the entire representation is bounded as described previously in (ii). Thus, we can clearly

attach each one of the representations to its respective portion of the model being built, rotated 90 degrees in counter-clockwise (see Figure 6). This concludes the proof. \Box

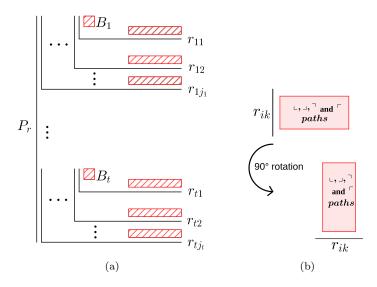


Figure 6: B_1 -EPG representation of G after induction step.

It is assumed in Theorem 1 that the blocks of G are B_1 -EPG. If, instead, it is assumed that the blocks of G are $_$ -EPG, we get an $_$ -EPG representation of a superclass of trees. The representation to be shown yields a distinct $_$ -representation of trees of the one described in [6].

Theorem 2. Let G be a graph such that every block of G is $_$ -EPG and every cut vertex v of G is a universal vertex in the blocks of G in which v is contained. Then, G is $_$ -EPG.

Proof. (Sketch) This proof follows the same reasoning lines as those in the proof of Theorem 1. However, the assumption that every block B_i is $_$ -EPG allows their EPG representations to be transformed into interval models. It is possible to show how to build an interval model of each block, given an $_$ -EPG representation of it. Furthermore, the EPG representations of the subtrees $T_{i1}, T_{i2}, \ldots, T_{ij_i}$ of B_i , for all i, obtained after the induction step can be transformed into $_$ -EPG models by 90 degree clockwise rotation so that the entire representation is $_$ -EPG.

A graph G is a block graph if every block of G is a clique. As a corollary of Theorem 2, block graphs are B_1 -EPG, a result proved in [1] using a proof by contradiction. Besides stronger, our proof is constructive, in the sense that it provides an $_$ -EPG representation.

Corollary 1. Block graphs are $_$ -EPG.

It is known that trees are $_$ -EPG. In [6], the authors described a recursive procedure to construct an $_$ -EPG representation of them. Note that trees are in particular block graphs and therefore can also be represented with the construction of Theorem 2. As an example, compare the resulting representations of both constructions, considering the tree T in Figure 7. The $_$ -EPG representation of T described in [6] is shown in Figure 8(a). And the $_$ -EPG representation of T given by Theorem 1 is shown in Figure 8(b).

Finally, note that the induction proof of Theorem 2 yields a recursive algorithm to produce an $_$ -EPG representation given as input a graph G holding the theorem conditions. This algorithm can be recognized in linear time, since the recognition of interval graphs (needed in order to obtain a model of each B'_i defined in the theorem's proof) can be done in linear time [3].

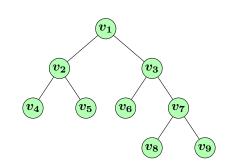


Figure 7: Tree T.

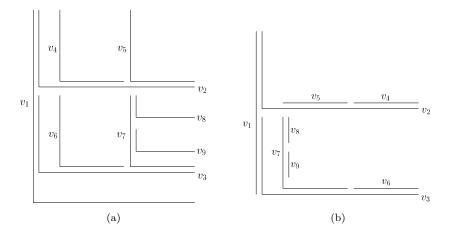


Figure 8: (a) $_$ -EPG representation of T. (b) Alternative $_$ -EPG representation of T.

3 A B₁-EPG representation of cactus graphs

A *cactus* is a connected graph in which every block is either an edge or a cycle. So, cactus graphs are another generalization of trees. In [5], the authors showed that a cactus is \Box -EPG. In this section, we provide an alternative construction that yields B₁-EPG representations of a cactus using BC-trees.

Theorem 3. Cactus graphs are B_1 -EPG.

Proof. (Sketch) This proof follows the same reasoning lines as those in the proof of Theorem 1. The difference here is that every block is either an edge or a cycle. It is possible therefore to construct B_1 -EPG representations of every block B_i . Furthermore, the B_1 -EPG representations of the subtrees $T_{i1}, T_{i2}, \ldots, T_{ij_i}$ of B_i , for all i, obtained after the induction step can be shown possible to be attached into vertical or horizontal regions of the cycle/edge so that the entire representation is B_1 -EPG.

It is known that the class of outerplanar graphs, which is a superclass of cactus graphs, is B_2 -EPG. It was conjectured by Biedl and Stern in [2] and proved by Heldt, Knauer and Ueckerdt in [9]. See an example of an outerplanar graph and its B_2 -EPG representation in Figure 9.

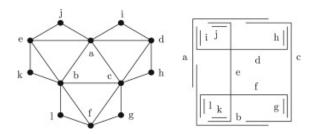


Figure 9: Outerplanar graph and its B_2 -EPG representation (see [9]).

4 Conclusion

In this paper, we showed a B₁-EPG representation of graphs in which every block is B₁-EPG and every cut vertex is a universal vertex in the blocks to which it belongs. We extend the proof to show that cactus graphs are also B₁-EPG. We also showed a linear-time algorithm to construct $_$ -EPG representations of graphs in which every block is $_$ -EPG and every cut vertex is a universal vertex in the blocks to which it belongs, concluding that block graphs are $_$ -EPG. The latter result provides an alternative $_$ -EPG representation for trees.

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